

Autonomous ground and aerial mobility,
on one autonomy stack.

ATEON Labs builds autonomous vehicles for ground that was never surveyed and airspace that was never mapped. Two platforms, one perception, planning and fleet stack.

COMPANY

LEGAL ENTITY	ATEON Labs Private Limited
CIN	U62011KA2025PTC207897
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REGISTERED OFFICE	No. 33, Shivapura Road, Bagalur Main Road, Kattigenahalli, Bengaluru 560064, Karnataka, India
FOUNDERS	Rishi Tejas KR, Co-founder & CEO Shiva U, Co-founder & CTO
PRESS	press@ateonlabs.com
WEB	ateonlabs.com

PLATFORMS

AGMS-X1 · Autonomous Ground Mobility System

Six-wheel articulated chassis with a hot-swap mission deck: cold-chain pod, secure parcel locker or open cargo bed. Rated 50 kg payload on a level, attitude-bounded deck; 125 kg gross vehicle weight. Climbs a 180 mm riser on a 280 mm tread holding the deck inside 5 degrees, crosses a 30 degree slope, and runs 8 hours mixed duty on one battery set.

AAMS-X1 · Autonomous Aerial Mobility System

Quad-rotor aerial platform targeting a 100 kg payload, with a four-bay underslung rack whose bays release independently, and optical-flow navigation for flight where satellite fix is unavailable.

OmegaMTL · Autonomy stack

One perception, planning and fleet stack across both domains, with a real-time safety partition running independently of the AI compute.

All platform figures are product requirements and design allocations from the current definition baseline, not measured field results.